

## AHM36A-S2QC000A30 AHS/AHM36

**ABSOLUTE ENCODERS** 





#### Ordering information

Туре	Part no.
AHM36A-S2QC000A30	1108589

Other models and accessories → www.sick.com/AHS\_AHM36

Illustration may differ



#### Detailed technical data

#### Performance

Number of steps per revolution (max. resolution)	16,384 (14 bit)
Number of revolutions	4,096 (12 bit)
$\label{eq:max} \begin{tabular}{ll} \textbf{Max. resolution (number of steps per revolution x number of revolutions)} \end{tabular}$	14 bit x 12 bit (16,384 x 4,096)
Error limits G	0.35° (at 20 °C) 1)
Repeatability standard deviation $\boldsymbol{\sigma_r}$	0.2° (at 20 °C) <sup>2)</sup>

<sup>1)</sup> In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

#### Interfaces

Communication interface	IO-Link
Communication Interface detail	IO-Link V1.1 / COM3 (230,4 kBaud)
Initialization time	2 s <sup>1)</sup>
Cycle time	≤ 3.2 ms
Smart Sensor	Efficient communication, Enhanced Sensing, diagnosis, Smart Task
Process data	Position, speed, electronic cams, limit values, linear position, linear speed, errors and warnings, switching signals on pin 2, Length, switching signals on pin 4
Parameterising data	Number of steps per revolution Number of revolutions PRESET Counting direction Sampling rate for speed calculation Unit for output of the speed value Round axis functionality Electronic cams(2 channels x 8 cams) Limit values Linear measuring length per 360° Pin 2 configuration

 $<sup>^{1)}</sup>$  Valid positional data can be read once this time has elapsed.

 $<sup>^{2)}</sup>$  In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

 $<sup>^{2)}</sup>$  Between input signal on pin 2 and associated output signal on pin 4.

	Configuration of length measurement (IO-Link mode) Configuration of length monitoring (IO-Link and SIO mode) Configuration of trigger after a defined length (SIO mode)
Available diagnostics data	Minimum and maximum temperature Maximumspeed Power-on counter Operatinghours counter power-on/motion Counter of direction changes/number of movements cw/number of movements ccw Minimum andmaximum operating voltage Distance covered Number of trigger signals on pin 2
Status information	Via status LED
Switching input/Switching output	<b>√</b>
Pin 2 input frequency	≤ 100 Hz
Pin 2 output frequency	≤ 100 Hz
Pin 4 output frequency	≤ 100 Hz
Latency	3.5 ms <sup>2)</sup>

 $<sup>^{1)}\,\</sup>mbox{\sc Valid}$  positional data can be read once this time has elapsed.

#### Electrical data

Connection type	Male connector, M12, 4-pin, universal
Supply voltage	18 30 V
Power consumption	≤ 1.5 W
Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	240 years (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Mechanical data

Mechanical design	Solid shaft, Servo flange
Shaft diameter	10 mm
Shaft length	12 mm
Weight	$0.12  \text{kg}^{ 1)}$
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Zinc
Start up torque	< 1 Ncm (+20 °C)
Operating torque	< 1 Ncm (+20 °C)
Permissible shaft loading	40 N (radial) 20 N (axial)
Operating speed	≤ 6,000 min <sup>-1</sup>
Moment of inertia of the rotor	2.5 gcm <sup>2</sup>
Bearing lifetime	3.6 x 10^8 revolutions
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$

 $<sup>^{1)}</sup>$  Based on devices with male connector.

 $<sup>^{2)}</sup>$  Between input signal on pin 2 and associated output signal on pin 4.

## AHM36A-S2QC000A30 | AHS/AHM36

#### ABSOLUTE ENCODERS

#### Ambient data

EMC	According to EN 61000-6-2, EN 61000-6-3 and EN 61131-9
Enclosure rating	IP66 (IEC 60529) IP67 (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +85 °C
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz 2,000 Hz (EN 60068-2-6)

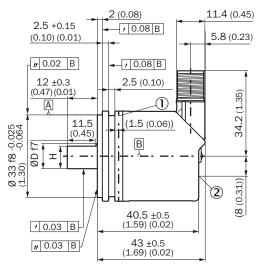
#### Smart Task

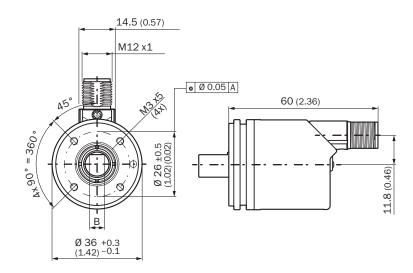
Smart Task name	Length measurement and trigger
Classifications	
ECLASS 5.0	27270502
ECLASS 5.1.4	27270502

LULAGG G.U	21210302
ECLASS 5.1.4	27270502
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270502
ECLASS 8.0	27270502
ECLASS 8.1	27270502
ECLASS 9.0	27270502
ECLASS 10.0	27270502
ECLASS 11.0	27270502
ECLASS 12.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

#### Dimensional drawing (Dimensions in mm (inch))

Solid shaft, servo flange, male connector

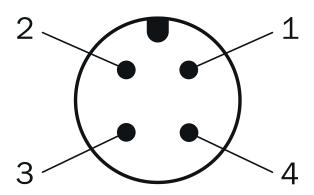




- ① Measuring point for operating temperature
- ② Measuring point for vibrations

Туре	Shaft diameter Ø D f7	В	н
AHx36x-S1xxxxxxxx AHx36x-S3xxxxxxxx	6 mm	3,6 mm	5,4 mm
AHx36x-S9xxxxxxx AHx36x-S5xxxxxxxx	8 mm	3,9 mm	7,5 mm
AHx36x-S2xxxxxxx AHx36x-S4xxxxxxxx AHx36x-SCxxxxxxxx	10 mm	6 mm	9 mm
AHx36x-SAxxxxxxxx AHx36x-S8xxxxxxxxx	1/4"	3,85 mm	5,7 mm
AHx36x-SBxxxxxxxx AHx36x-S7xxxxxxxx	3/8"	4,35 mm	9 mm

#### PIN assignment



PIN	Wire color	Signal	Function		
			Basic	Advanced	Advanced Smart Task
1	Brown	L+	Encoder supply voltage 18-30 V (+Us)		
2	White	I/Q	Not connected - no function	cted - no Multifunctional pin (configurable as switching input or switching output)	
3	Blue	Ŀ	Encoder supply voltage 0 V (GND)		
4	Black	C/Q	IO-Link communication		
			-		Switching output (SIO mode)

#### Recommended accessories

Other models and accessories → www.sick.com/AHS\_AHM36

	Brief description	Туре	Part no.		
Distributors					
See To	<ul> <li>Connection type head A: Male connector, M12, 4-pin, A-coded</li> <li>Connection type head B: Female connector, M12, 4-pin, A-coded</li> <li>Connection type head C: Female connector, M12, 4-pin, A-coded</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 0.11 m, PVC</li> <li>Description: Sensor/actuator cable, Y-Junction, 2 x female connector M12, 4-pin, straight, 0.11 m PVC-cable, 1 x male connector M12, 4-pin, straight, to connect SICK Sensors with SICK Smart Sensors</li> <li>Note: T-coupler 2 x M12 female + M12 male straight with cable</li> </ul>	SYL-1204-G0M11-X1	6055011		
Plug connecto	rs and cables				
	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight</li> <li>Description: Unshielded, Head A: female connector, M12, 4-pin, straight, unshielded, for power supply, for cable diameter 4 mm 6 mm Head B: -</li> <li>Connection systems: Screw-type terminals</li> <li>Permitted cross-section: ≤ 0.75 mm²</li> </ul>	DOS-1204-G	6007302		
Shaft adaptat	ion				
	Bellows coupling, shaft diameter 6 mm / 10 mm, maximum shaft offset: radial $\pm$ 0.25 mm, axial $\pm$ 0.4 mm, angular +/- 4°; max. speed 10,000 rpm, -30 °C to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum hub	KUP-0610-B	5312982		
	Double loop coupling, shaft diameter 6 mm $/$ 10 mm, max. shaft offset: radially +/- 2,5 mm, axially +/-3 mm, angle +/- 10 degrees;max. speed 3.000 rpm, -30 to +80 degrees Celsius, torsional spring stiffness of 25 Nm/rad	KUP-0610-D	5326697		
(c)	Spring washer coupling, shaft diameter 6 mm / 10 mm, Maximum shaft offset: radial $\pm$ 0.3 mm, axial $\pm$ 0.4 mm, angular $\pm$ 0.5°; max. speed 12,000 rpm, $\pm$ 10° to $\pm$ 80°C, max. torque 60 Ncm; material: aluminum flange, glass fiber-reinforced polyamide membrane and hardened steel coupling pin	KUP-0610-F	5312985		
	Claw coupling, shaft diameter 6 mm / 10 mm, damping element 80 shore blue, maximum shaft offset: radial $\pm$ 0.22 mm, axial $\pm$ 1 mm angular $\pm$ 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, –30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0610-J	2127056		
10	Double loop coupling, shaft diameter 8 mm $/$ 10 mm, max. shaft offset: radially +/-0,25 mm, axially +/-0,4 mm, angle +/- 4 degrees;max. speed 10.000 rpm, -30 to +120 degrees Celsius, torsional spring stiffness of 150 Nm/rad	KUP-0810-D	5326704		

	Brief description	Туре	Part no.
<b>Vo</b>	Claw coupling, shaft diameter 8 mm $/$ 10 mm, damping element 80 shore blue, maximum shaft offset: radial $\pm$ 0.22 mm, axial $\pm$ 1 mm angular $\pm$ 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, $-$ 30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-0810-J	2128267
	Bellows coupling, shaft diameter 10 mm/10 mm; maximum shaft offset: radial +/- 0.25 mm, axial +/- 0.4 mm, angular +/- $4^\circ$ ; max. revolutions 10,000 rpm, -30° to +120 °C, max. torque 120 Ncm; material: stainless steel bellows, aluminum clamping hubs	KUP-1010-B	5312983
<b>(</b>	Double loop coupling, shaft diameter 10 mm / 10 mm, Maximum shaft offset: radial +/- 2.5 mm, axial +/- 3 mm, angular +/- 10°; max. speed 3,000 rpm, -30° to +80 °C, max. torque 1.5 Nm; material: polyurethane, galvanized steel flange	KUP-1010-D	5326703
	Claw coupling, shaft diameter 10 mm $/$ 10 mm, damping element 80 shore blue, maximum shaft offset: radial $\pm$ 0.22 mm, axial $\pm$ 1 mm angular $\pm$ 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, $-$ 30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-1010-J	2127054
	10~mm/12~mm; maximum shaft offset: radial +/- 0.25 mm, axial +/- 0.4 mm, angular +/- 4°; max. revolutions 10,000 rpm, -30° to +120°C, max. torque 120 Ncm; material: stainless steel bellows, aluminum clamping hubs	KUP-1012-B	5312984
10	Double loop coupling, shaft diameter 10 mm / 12 mm, Maximum shaft offset: radial +/- 2.5 mm, axial +/- 3 mm, angular +/- 10°; max. speed 3,000 rpm, -30° to +80 °C, max. torque 1.5 Nm; material: polyurethane, galvanized steel flange	KUP-1012-D	5326702
	Claw coupling, shaft diameter 10 mm / 12 mm, damping element 80 shore blue, maximum shaft offset: radial $\pm$ 0.22 mm, axial $\pm$ 1 mm angular $\pm$ 1.3°, max. speed 19,000 rpm, angle of twist max. 10°, –30 °C to +80 °C, max. torque 800 Ncm, tightening torque of screws: ISO 4029 150 Ncm, material: aluminum flange, damping element: polyurethane	KUP-1012-J	2128265
Others			
10 to	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight, A-coded</li> <li>Connection type head B: Male connector, M12, 4-pin, straight, A-coded</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 2 m, 4-wire, PUR, halogen-free</li> <li>Description: Sensor/actuator cable, unshielded</li> <li>Application: Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14- 020UB3M2A14	2096000
10 10	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight, A-coded</li> <li>Connection type head B: Male connector, M12, 4-pin, straight, A-coded</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 5 m, 4-wire, PUR, halogen-free</li> <li>Description: Sensor/actuator cable, unshielded</li> <li>Application: Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14- 050UB3M2A14	2096001
10 to	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight, A-coded</li> <li>Connection type head B: Male connector, M12, 4-pin, straight, A-coded</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 10 m, 4-wire, PUR, halogen-free</li> <li>Description: Sensor/actuator cable, unshielded</li> <li>Application: Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14- 100UB3M2A14	2096002
No.	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight, A-coded</li> <li>Connection type head B: Flying leads</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 2 m, 4-wire, PUR, halogen-free</li> <li>Description: Sensor/actuator cable, unshielded</li> <li>Application: Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14- 020UB3XLEAX	2095607

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	Brief description	Туре	Part no.
No.	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight, A-coded</li> <li>Connection type head B: Flying leads</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 5 m, 4-wire, PUR, halogen-free</li> <li>Description: Sensor/actuator cable, unshielded</li> <li>Application: Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14- 050UB3XLEAX	2095608
No.	<ul> <li>Connection type head A: Female connector, M12, 4-pin, straight, A-coded</li> <li>Connection type head B: Flying leads</li> <li>Signal type: Sensor/actuator cable</li> <li>Cable: 10 m, 4-wire, PUR, halogen-free</li> <li>Description: Sensor/actuator cable, unshielded</li> <li>Application: Zones with oils and lubricants, Drag chain operation, Robot</li> </ul>	YF2A14- 100UB3XLEAX	2095609

#### SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

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